## PRODUCT DATA SHEET

# ACTUATOR LA32

## Features and options:

- 24V DC permanent magnet motor
- Thrust up to 6000 N (with ball screw)
- Stainless steel piston rod
- High-strength plastic housing protects motor and gears
- Elegant and compact design with small installation dimensions
- Protection class: IPX1
- Colour: black
- 2250 mm straight cable with 6.3 mm jack plug
- Low noise level: 46 dB (A); measuring method DS/EN ISO 3746, actuator not loaded
- LA32K with ball screw and double-acting brake (i.e. push and pull/both directions)

Golf

- Protection class: IPX5 or IPX6
- Reed-switch for exact positioning (8 pulses per spindle revolution)
- LA32 with 5mm. pitch F: Manual quick release
- LA32 with 5mm. pitch FH: Manual quick release with dampened movement
- Mechanical splines function (push only)
- Electrical splines function, built-in micro-switch in back fixture, the actuator can therefore only be used for push. (Only on 01 and 02 back fixture)
- LA32K with ball screw and double-acting brake (i.e. push and pull/both directions)
- LA32KAS with ball screw and safety nut
- LA32KSM with ball screw, safety nut and mechanical splines
- Available with 0.2 m or 0.4 m coiled cable
- LA32JKSM available with 2-speed facility for the LINAK JUMBO SYSTEM
- CS32; electronic limit switch (built-in)

# Usage:

- Duty cycle: Max. 10% or 2 minutes continuous use followed by 18 min. not in use
- Ambient temperature +5° to +40° C
- For use with LINAK control boxes CB8, CB12, CB14 and CS16 PCB or internal CS32 PCB
- Should LA32 be used with a non LINAK control unit, please ask the nearest LINAK representative for further details

#### Accessories::

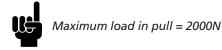
- CS16; electronic limit switch
- Optical encoder
- SLS: safety limit switch

The LA32 is a powerful actuator that can be supplied with a ball screw spindle to give outstanding performance. The ideal choice for a wide range of applications including adjustment of hospital beds.

The LA32 has many special options including a safety nut, splines, quick release (F) and an optional protection class up to IPX6 standard.



MEDLINE



# **Technical specifications:**

Туре	Spindle pitch (mm)	Thrust max. Push [N]	*Self- lock Max. [N]*	Stroke length [mm]					Typical Speed 0/full load [mm/s]	Typical amp. 24V at full load [A]		
321xxx+00xxx4xx	3	4000	4000	100 <sup>°</sup>	150°	200°	250°	300°	350	400	7/5.5	3.5
322xxx+00xxx4xx	6	3000	2000	100 <sup>°</sup>	150°	200 <sup>°</sup>	250 <sup>°</sup>	300 <sup>°</sup>	350°	400 <sup>°</sup>	13.8/13 (2000N)	3 (2000N)
322xxx+40xxx4xx	6	3000	3000	100 <sup>°</sup>	150°	200 "	250°	300°	350	400	13.6/8.5	4.5
32Kxxx+x0xxx4xx	4	6000	6000	-	150°	200°	250°	300°	350	400	8.7/6.8	4.7
32Kxxx+10xxx4xx	4	6000	6000	-	150°	200°	250°	300°	350	400	8.7/6.8	4.7
32Kxxx+30xxx4xx	4	6000	6000	-	-	-	-	300 <sup>°</sup>	350	400	8.7/6.8	4.7
328xxF+x0xxx4xx	5	2800	2800	100 °	150 <sup>°</sup>	200	250#	300#	-	-	11/9.8	3.5
32Kxxx+30xxx3xx	4	7500	6500	-	-	-	-	300°	350	400	15/6.5 (7500N)	9.5 (7500N)

The above measurements are made in connection with a CB12, the LA32JKSM with a CBJ1 high speed.

P = Stroke lengths where potentiometer is possible as standard

\* LINAK control boxes are designed so that they will short-circuit the motor terminals (poles) of the actuator(s) when the actuator(s) are not running. This solution gives the actuator(s) a higher self-locking ability. If the actuator(s) are not connected to a LINAK control box the terminals of the motor must be short-circuited to achieve the above mentioned self-locking ability.

# = Not with spindle potentiometer (stroke length max. 220 mm)

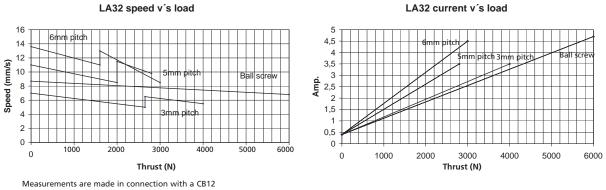
- K = Ball screw
- KAS = Ball screw with safety nut
- **KSM** = Ball screw with splines and safety nut
- **R** = Reed-switch
- F = Manual quick release
- **FH** = Manual quick release with dampened movement

KAS and KSM are only available on LA32K (with ball screw)

LA32 Ordering example:

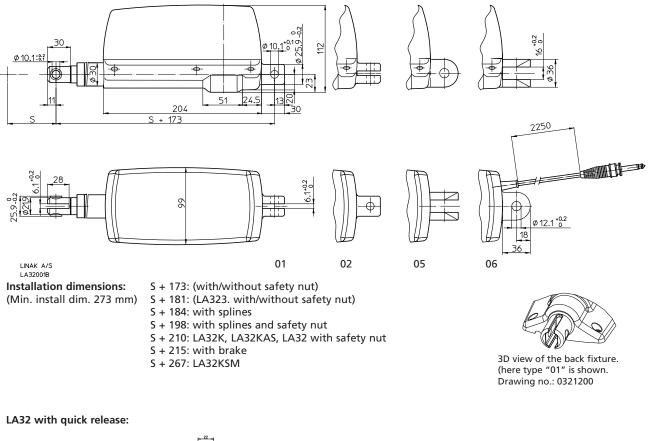
$\frac{32}{1} \frac{1}{1} \frac{1}{1} \frac{0}{1} \frac{0}{1} \frac{0}{1} + \frac{1}{1} \frac{0}{1} \frac{250}{1} \frac{40}{1} \frac{0}{1} \frac{0}{1}$									
	Cables:	Jack cable (General told 0 = *Straight 2.3 m 1 = *Straight 1.05 m 2 = *Coiled 0.4 m 3 = *Coiled 0,2 m 4 = Straight without pl	e +/- 0.07m) = Straight without plug 1 m (CS) always black = *Other cablel/ length always the same colour as the actuator m (Potentiometer) always black						
	Protection Class:	0 = IPX1 1 = IPX5 2 = IPX6 Washable							
	Motor type:	0 = 24V 1 = 24V S-motor 2 = 12V S-motor 3 = 24V Jumbo motor	<ul> <li>4 = 24V L-motor standard motor, will always have to be chosen for use with a LINAK control box.</li> <li>5 = 12V motor</li> </ul>						
	Stroke length:XXX = mm Max. 400 mm for 3-6 mm pitch (up to 600 mm with special Max. 500 mm for 9-12 mm pitch (up to 600 mm with special Min. 100 mm								
	Install. dim.	0 = Standard X = Other install. dim.							
	Option:	1 = Safety nut RECOMN 0 = None 2 = Steel splines 3 = Steel splines with sa	4 = Brake 5 = Brake with safety nut						
	Colour:	+ = Grey -  = Black							
	Option:	0 = None F = Quick release (F)	H = Quick release, dampened movement(FH)						
	Positioning C/S Optical encoder:	0 = None P = Potentiometer 1 ko L = Potentiometer 5 Ko T = Potentiometer 10 K Y = CS 32A mount. (No Z = CS 32B mount. C = CS 32C mount.	hm D = Optical encoder ohm						
	Back Fixture:	1 = Standard 2 = Turned 90 degrees A = Standard with El-sp B = Turned 90 degrees							
	Spindle type:	$\begin{array}{l} 1 = 3 \mbox{ mm} & (1 \mbox{ thread} \\ 2 = 6 \mbox{ mm} & (2 \mbox{ thread} \\ 3 = 9 \mbox{ mm} & (3 \mbox{ thread} \\ 4 = 4 \mbox{ mm} & (2 \mbox{ thread} \\ 5 = 2,5 \mbox{ mm} & (1 \mbox{ thread} \\ \end{array}$	ded) 8 = 5 mm (2-threaded) ded) K = Ball spindle ded)						
	Actuator type:	32 = LA32							

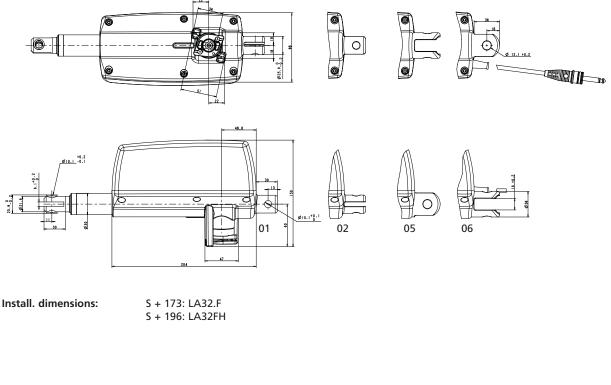
Graphs:



LA32 current v's load

Dimension:





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